



ELECTRONICS ENGINEERING DEPARTMENT

Measurement

Hand Notes For Electronics Engineering Department

HAND NOTES

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MEASUREMENTSBASICS :

$$A_t = 10 \text{ A} \quad (\text{True value})$$

$$A_m = 9.8 \text{ A} \quad (\text{Measured value}).$$

$$\begin{aligned} \text{Static error} &= A_m - A_t \\ (8\text{A}) &= 9.8 - 10 = -0.2 \text{ A} \end{aligned}$$

$$\text{Static correction } (\delta_c) = -\delta A$$

$$= -(-0.2) = 0.2 \text{ A}.$$

Correction is to be done for A_m to get A_t .

$$\begin{aligned} 2 \text{ A} \pm 1 \text{ A} &\left. \begin{array}{l} \text{not} \\ \text{good} \end{array} \right\} \rightarrow 50\% \text{ error} \\ 1000 \text{ A} \pm 10 \text{ A} &\left. \begin{array}{l} \text{good} \end{array} \right\} \rightarrow 1\% \text{ error} \end{aligned}$$

$$\text{Relative static error} = \frac{A_m - A_t}{A_t}$$

Accuracy:

It is a measure of closeness with which an instrument reading approaches the true value of the quantity being measured (Mesurand).

precision:

Reproducibility of measurements.

Mesurand: quantity under measurement.

Sensitivity:-

It is the ratio of magnitude of o/p signal to the mag. of i/p signal under measurement.

Dead time:-

It is the time required by a measurement system to respond to change in the measurement. dead time depends on damping factor selected

for meter. range : 0.6 to 0.8. ($\xi < 1$ under damped with $\xi, 0.6 \text{ to } 0.8$)
Dead zone :-

It is the largest change of input quantity for which there is no output of the instr.

Resolution or Discrimination :-

The smallest increment in input which can be detected with certainty by an instr. is known as Resolution.

$R_1 = 1000 \Omega \pm 10\Omega$	990	1010
$R_2 = 500 \Omega \pm 5\Omega$	495	505
	(990 + 495)	(1010 + 505)
$R_1 + R_2 = 1500 \pm 15$	1485	1515
	485	515
$R_1 - R_2 = 500 \pm 15$	(990 - 505)	(1010 - 495)

* Resultant error in addition & subtraction of quantity can be obtained by adding all individual errors. They should be expressed in absolute values.

$$V = 230V \pm 2\%$$

$$I = 10A \pm 1\%$$

$$P = 2300 \pm 3\% \quad (V \cdot I)$$

$$R = 23 \pm 3\% \quad \left(\frac{V}{I}\right)$$

* Resultant error in product & division of quantities can be obtained by adding all individual errors. and they should be expressed in percentage values.

$$I = 10 \text{ A} \pm 2\%$$

$$R = 500 \Omega \pm 3\%$$

$$\begin{aligned} \text{Then power } P &= I^2 R \\ &= 50000 \pm [2 \times 2\% + 1 \times 3\%] \\ &= 50000 \pm 7\% \end{aligned}$$

Resultant error in polynomials can be obtained by the above method.

NOTE:

It is preferable to measure the quantity instead of calculation. In the calculation of quantity the error will be more.

eg: $V \Rightarrow 2\%$
 $I \Rightarrow 1\%$
 $P \Rightarrow 3\%$
By meters $\Rightarrow Pf \Rightarrow 2\%$

By calculation,
 $Pf = \frac{P}{VL} = 6\%$

Types of errors :-

(a). Gross errors :-

This class of errors mainly comes by human mistakes in reading, recording and calculating the measurements.

(b). Systematic errors :

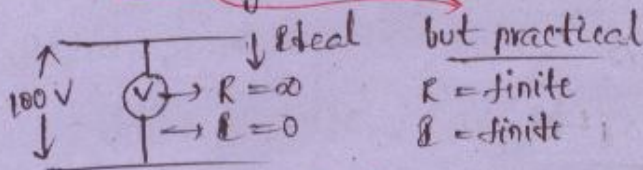
(i). Instrumental errors :-

→ Due to inherent short comings { errors in instr. }

→ Misuse of instr.

$$\begin{array}{l} 1.2 \text{ A} \\ 0 - 5 \text{ A } \textcircled{I} \checkmark \\ 0 - 100 \text{ A } \textcircled{II} \end{array}$$

→ Loading effects



(2). Environmental Error :-

Due to temp, electro magnetic effects.

(3). Observational Error :-

↳ parallax error

(c). Random Error :-

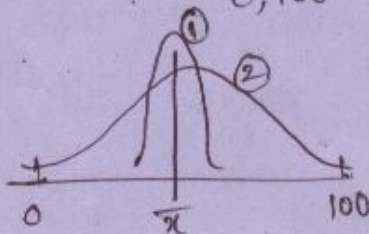
→ These error occurs due to unknown source or cumulative of different sources together.

→ Random errors can be compensated by statistical Analysis.

↳ Mean $\bar{x} = \frac{x_1 + x_2 + \dots + x_n}{n}$

Eg: $51, 49 \rightarrow \bar{x} = 50$

$0, 100 \rightarrow \bar{x} = 50 \leftarrow \text{not advisable.}$



$$d_1 = x_1 - \bar{x}$$

$$d_2 = x_2 - \bar{x}$$

$$\vdots$$

$$d_n = x_n - \bar{x}$$

$$\text{Avg. deviation} = \frac{|d_1| + |d_2| + \dots + |d_n|}{n}$$

$$(6) \text{ std. deviation} = \sqrt{\frac{d_1^2 + d_2^2 + \dots + d_n^2}{n}}$$

$$(8) \text{ Variance} = (\text{s.d})^2$$

True value: of the quantity to be measured may be ~~def~~ defined as an avg. of infinite no. of measured values when the avg. deviation due to various contributing factors tends to be zero.

1.1). $A_m = 6.7 \text{ A}$

$A_t = 6.54 \text{ A}$

Error = $A_m - A_t$

(δA) = 0.16 A

Correction factor $\delta c = -\delta A$
 $= -0.16 \text{ A}$

1.2). Range : $0 - 2.5 \text{ V}$

$A_t = 1.5 \text{ V}$

$A_m = 1.46 \text{ V}$

Error $\delta A = A_m - A_t$

$= -0.04 \text{ V}$

Correction $\delta c = -\delta A$

$= 0.04 \text{ V}$

% Error = $\frac{-0.04}{1.5} \times 100$

$= -2.67 \%$

% Error = $\frac{-0.04}{2.5} \times 100$ (w.r.t. full scale).

$= -1.6 \%$

1.3).

$R = 5000 \pm 10 \%$

$= (5000 \pm 500) \Omega$

$\Rightarrow R = 4500 \Omega \text{ to } 5500 \Omega$

1.4).

$(0 - 10) \text{ A} \rightarrow 1.5 \%$

Error = $10 \times \frac{1.5}{100}$

$= 0.15 \text{ A}$