



ELECTRONICS ENGINEERING DEPARTMENT

Measurement

Hand Notes For Electronics Engineering Department

HAND NOTES

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* SAT. 15/11/08 *

MEASUREMENTS

BASICS :

$$A_t = 10 \text{ A (True value)}$$

$$A_m = 9.8 \text{ A (Measured value)}$$

$$\boxed{\text{Static error} = A_m - A_t}$$

$$(\delta A) = 9.8 - 10 = -0.2 \text{ A}$$

$$\text{Static correction } (\delta C) = -\delta A$$

$$= -(-0.2) = 0.2 \text{ A}$$

Correction is to be done for A_m to get A_t .

$$\left. \begin{array}{l} 2 \text{ A} \pm 1 \text{ A} \\ \rightarrow 50\% \text{ error} \end{array} \right\} \begin{array}{l} \text{not} \\ \text{good} \end{array}$$

$$\left. \begin{array}{l} 1000 \text{ A} \pm 10 \text{ A} \\ \rightarrow 1\% \text{ error} \end{array} \right\} \text{good}$$

$$\boxed{\text{Relative static error} = \frac{A_m - A_t}{A_t}}$$

Accuracy :

It is a measure of closeness with which an instrument reading approaches the true value of the quantity being measured (Mesurand).

precision :

Reproducibility of measurements.

Mesurand : quantity under measurement.

Sensitivity :-

It is the ratio of magnitude of o/p signal to the mag. of i/p signal under measurement.

Dead time :-

It is the time required by a measurement system to respond to change in the measurement. dead time depends on damping factor selected

for meter. range : 0.6 to 0.8. ($\xi < 1$
Dead zone :- under damped
 with $\xi, 0.6 \text{ to } 0.8$)

It is the largest change of 1/p quantity for which there is no o/p of the instr.

Resolution or Discrimination :-

The smallest increment in 1/p which can be detected with certainty by an instr. is known as Resolution.

$R_1 = 1000 \Omega \pm 10\Omega$	990	1010
$R_2 = 500 \Omega \pm 5\Omega$	495	505
$R_1 + R_2 = 1500 \pm 15$	(990 + 495)	(1010 + 505)
	1485	1515
$R_1 - R_2 = 500 \pm 15$	485	515
	(990 - 505)	(1010 - 495)

* Resultant error in addition & subtraction of quantity can be obtained by adding all individual errors. They should be expressed in absolute values.

$$V = 230V \pm 2\%$$

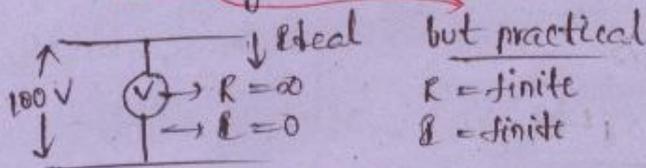
$$I = 10A \pm 1\%$$

$$P = 2300 \pm 3\% \quad (V \cdot I)$$

$$R = 23 \pm 3\% \quad \left(\frac{V}{I}\right)$$

* Resultant error in product & division of quantities can be obtained by adding all individual errors and they should be expressed in percentage values.

→ Loading effects



(2). Environmental Errors :-

Due to temp, electro magnetic effects.

(3). Observational Errors :-

↳ parallax error

(c). Random Errors :-

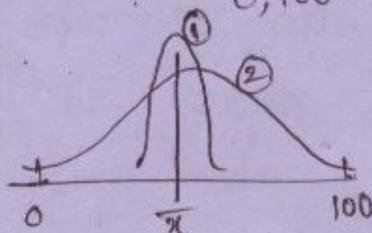
→ These error occurs due to unknown source or cumulative of different sources together.

→ Random errors can be compensated by statistical Analysis.

↳ Mean $\bar{x} = \frac{x_1 + x_2 + \dots + x_n}{n}$

Eg: 51, 49 → $\bar{x} = 50$

0, 100 → $\bar{x} = 50$ ← not advisable.



$$d_1 = x_1 - \bar{x}$$

$$d_2 = x_2 - \bar{x}$$

⋮

$$d_n = x_n - \bar{x}$$

$$\text{Avg. deviation} = \frac{|d_1| + |d_2| + \dots + |d_n|}{n}$$

$$(6) \text{ std. deviation} = \sqrt{\frac{d_1^2 + d_2^2 + \dots + d_n^2}{n}}$$

$$(7) \text{ Variance} = (\text{s.d.})^2$$

True value: of the quantity to be measured may be ~~the~~ defined as an avg. of infinite no. of measured values when the avg. deviation due to various contributing factors tends to be zero.

$$1.1). \quad A_m = 6.7 \text{ A}$$

$$A_t = 6.54 \text{ A}$$

$$\text{Error} = A_m - A_t$$

$$(\delta A) = 0.16 \text{ A}$$

$$\text{Correction factor } \delta C = -\delta A$$

$$= -0.16 \text{ A}$$

$$1.2). \quad \text{Range : } 0 - 2.5 \text{ V}$$

$$A_t = 1.5 \text{ V}$$

$$A_m = 1.46 \text{ V}$$

$$\text{Error } \delta A = A_m - A_t$$

$$= -0.04 \text{ V}$$

$$\text{Correction } \delta C = -\delta A$$

$$= 0.04 \text{ V}$$

$$\% \text{ Error} = \frac{-0.04}{1.5} \times 100$$

$$= -2.67 \%$$

$$\% \text{ Error} = \frac{-0.04}{2.5} \times 100 \quad (\text{w.r.t. full scale})$$

$$= -1.6 \%$$

1.3).

$$R = 5000 \pm 10\%$$

$$= (5000 \pm 500) \Omega$$

$$\Rightarrow R = 4500 \Omega \text{ to } 5500 \Omega$$

1.4).

$$(0 - 10) \text{ A} \rightarrow 1.5\%$$

$$\text{Error} = 10 \times \frac{1.5}{100}$$

$$= 0.15 \text{ A}$$